
mipea Documentation

Release 2.0.0

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Contents

1	Installation	1
1.1	Download the configure script	1
1.2	Building the configure script	1
1.3	Troubleshooting	2
2	Peripherals	3
2.1	Macros	3
2.2	Functions	3
3	Clock Manager	5
3.1	Registers	5
3.2	Enums	6
3.3	Global Variables	6
3.4	Functions	6
4	GPIOs	7
4.1	Registers	7
4.2	Enums	8
4.3	Functions	8
5	I2C	11
5.1	Registers	11
5.2	Functions	11
6	PWM	13
6.1	Macros	13
6.2	Registers	13
6.3	Enums	14
6.4	Structs	14
6.5	Functions	15
7	SPI	17
7.1	Registers	17
7.2	Structs	17
7.3	Functions	18
8	Timer	21

8.1	Registers	21
8.2	Functions	21
9	Mipea Wrapper	23
9.1	Functions	23
10	License	25
11	Documentation License	27
12	Indices and tables	35
	Index	37

The source code is hosted on [GitHub](#). mipea uses autotools (autoconf, automake, libtool) to build and install the library. The git repository does *not* include the `configure` script and `Makefile.in` which means that you have two options for installing the library.

1.1 Download the configure script

On [GitHub](#), when you look under the tab [releases](#) you will find some release with a name like for example “v2.0.0”. Then you can download the corresponding file named “mipea_x.x.x” which *includes the configure script and Makefile.in*. After downloading just run these commands from inside the downloaded directory:

```
$ ./configure
$ make
$ sudo make install
```

1.2 Building the configure script

When you have the GNU autotools installed you can simply clone this repository and build the `configure` script and `Makefile.in` yourself:

```
$ git clone https://github.com/jasLogic/mipea.git
$ cd mipea
$ autoreconf --install
$ ./configure
$ make
$ sudo make install
```

1.3 Troubleshooting

1.3.1 Configure script can not find /proc/cpuinfo

If the configure script prints this warning:

```
configure: WARNING: cannot find file /proc/cpuinfo
```

than the script was unable to find the `cpuinfo` file which is needed to determine the SoC (BCM2835 or BCM2836/7) and the revision. Pis with a revision number where the last four digits are less than 0004 use I2C bus 0 instead of 1, like the new ones.

This error can be fixed by editing the `config.h` file ensuring that it contains these lines (depending on your Pi):

```
#define BCM2835      1
#define BCM2836_7    1
#define USE_I2C_BUS_0 1
```

1.3.2 When running a program, the shared library file is not found

I noticed that sometimes the library can be linked, but when running a program an error message appears saying: File or directory not found. If you have this problem just run `ldconfig` or follow the output from `sudo make install`:

```
-----
Libraries have been installed in:
    /usr/local/lib

If you ever happen to want to link against installed libraries
in a given directory, LIBDIR, you must either use libtool, and
specify the full pathname of the library, or use the '-LLIBDIR'
flag during linking and do at least one of the following:
    - add LIBDIR to the 'LD_LIBRARY_PATH' environment variable
      during execution
    - add LIBDIR to the 'LD_RUN_PATH' environment variable
      during linking
    - use the '-Wl,-rpath -Wl,LIBDIR' linker flag
    - have your system administrator add LIBDIR to '/etc/ld.so.conf'

See any operating system documentation about shared libraries for
more information, such as the ld(1) and ld.so(8) manual pages.
-----
```

1.3.3 Wifi stops working when using the library

In versions 2.1.0 and below the GPIO map and unmap functions cleared *all* pullup / -downs on all pins. This could lead to the wifi not working until a reboot. This issue should be fixed with version 2.1.1.

The peripheral functions are something like the *core* of the library. They map and unmap the memory used by all other parts.

2.1 Macros

PERIPHERAL_BASE_BCM2835

```
0x20000000
```

This macro holds the value of the peripheral base, when a BCM2835 is used.

PERIPHERAL_BASE_BCM2836_7

```
0x3F000000
```

This macro holds the value of the peripheral base, when a BCM2836 or BCM2837 is used.

2.2 Functions

int **peripheral_map** (volatile uint32_t **map, uint32_t offset, uint32_t size)

This function maps a code memory block of size `size` at offset `offset` from the peripheral base.

Note: The `offset` must be a multiple of the page size which is 4096 on the Raspberry Pi.

The function returns 0 on success and -1 on error.

void **peripheral_unmap** (void* map, uint32_t size)

This function unmaps the memory mapped to pointer `map` with size `size`.

int **peripheral_ismapped** (void **map*, uint32_t *size*)

This function checks if a pointer `map` is already mapped to a memory region with the size `size`. It returns `true` if the pointer is already mapped and `false` if not.

CHAPTER 3

Clock Manager

3.1 Registers

struct **clock_manager_register_map**

This struct maps the registers of the clock manager. The names of the struct members correspond to the registers. Unfortunately, the official datasheet does not feature this chapter. But there is an upload of this chapter here: [BCM2835 clocks](#):

```
struct clock_manager_register_map {
    uint32_t GP0CTL;
    uint32_t GP0DIV;
    uint32_t GP1CTL;
    uint32_t GP1DIV;
    uint32_t GP2CTL;
    uint32_t GP2DIV;
    uint32_t: 32;
    uint32_t: 32;
    uint32_t: 32;
    uint32_t: 32;
    uint32_t PCMCTL;
    uint32_t PCMDIV;
    uint32_t PWMCTL;
    uint32_t PWMDIV;
}
```

extern volatile struct *clock_manager_register_map* ***CM**

```
CM = (volatile struct clock_manager_register_map *) (clock_manager_base_ptr + 28);
```

By using this variable, the registers of the clock manager can be accessed like this `CM->PWMCTL`.

3.2 Enums

3.2.1 Clock sources

This enum holds the values for the different clock sources:

```
enum {
    CLOCK_GND,
    CLOCK_OSC,
    CLOCK_TST0,
    CLOCK_TST1,
    CLOCK_PLLA,
    CLOCK_PLLC,
    CLOCK_PLLD,
    CLOCK_HDMI
};
```

3.3 Global Variables

extern const uint32_t CM_PASSWD;

```
const uint32_t CM_PASSWD = 0x5A000000;
```

This variable holds the clock manager password. This value must always be present when writing to a clock manager register (e.g. by OR with the value).

3.4 Functions

int **clock_map** (void)

This function maps the clock manager registers. It calls `peripheral_map()` with the values `CLOCK_MANAGER_OFFSET` and `CLOCK_MANAGER_SIZE`. On error -1 is returned.

void **clock_unmap** (void)

This function unmaps the clock manager.

The following functions all take a pointer to a clock manager register as an argument because all the registers for the *different clocks* have the *same structure*. This means that you just need to tell the clock manager which clock to use (by pointing to the right register). For example: `clock_enable (&CM->PWMCTL);`

void **clock_enable** (volatile uint32_t *reg)

This function enables the clock with the register pointed to by `reg`.

void **clock_disable** (volatile uint32_t *reg)

This function disables the clock with the register pointed to by `reg`.

void **clock_configure** (volatile uint32_t *reg, clock_source_t src, unsigned int divisor, unsigned int mash)

This function configures the clock with the register pointed to by `reg` and sets up the `clock_source_t` `src`, the divisor `divisor` with the mash factor `mash`.

Todo: Add a decimal places to the divisor.

4.1 Registers

struct **gpio_register_map**

This struct maps the registers of the GPIOs. The names of the struct members correspond to the registers from the [Datasheet](#):

```
struct gpio_register_map {
    uint32_t FSEL[6];
    uint32_t: 32;
    uint32_t SET[2];
    uint32_t: 32;
    uint32_t CLR[2];
    uint32_t: 32;
    uint32_t LEV[2];
    uint32_t: 32;
    uint32_t EDS[2];
    uint32_t: 32;
    uint32_t REN[2];
    uint32_t: 32;
    uint32_t FEN[2];
    uint32_t: 32;
    uint32_t HEN[2];
    uint32_t: 32;
    uint32_t LEN[2];
    uint32_t: 32;
    uint32_t AREN[2];
    uint32_t: 32;
    uint32_t AFEN[2];
    uint32_t: 32;
    uint32_t PUD;
    uint32_t PUDCLK[2];
    // BCM2711 only
    uint32_t: 32;
}
```

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```
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t: 32;
uint32_t PUPPDN[4];
};
```

extern volatile struct *gpio_register_map* *GP

```
GP = (volatile struct gpio_register_map *)gpio_base_ptr;
```

By using this struct, the registers of the GPIOs can be accessed like this GP->SET[0].

4.2 Enums

4.2.1 Pin functions

This enum holds the values for the various pin functions:

```
enum {
    INPUT, OUTPUT, ALT0, ALT1, ALT2, ALT3, ALT4, ALT5
};
```

4.2.2 Pullup / -downs

This enum holds the values for the states of the pullups / -downs:

```
enum {
    PUD_DISABLE, PUD_DOWN, PUD_UP
};
```

4.3 Functions

int **gpio_map**(void)

This function maps the GPIO registers. It calls *peripheral_map()* with the values GPIO_OFFSET and GPIO_SIZE. On error -1 is returned.

void **gpio_unmap** (void)

This function unmaps the GPIOs.

void **gpio_func** (uint32_t *pin*, int *function*)

This function sets the pin *pin* to the pin function *function*.

void **gpio_set** (uint32_t *pin*)

Set the pin *pin*.

void **gpio_clr** (uint32_t *pin*)

Clear the pin *pin*.

uint32_t **gpio_tst** (uint32_t *pin*)

Test the pin *pin*. This function returns 0 or false when the pin is low and non-zero if the pin is high.

void **gpio_pud** (uint32_t *pin*, int *pud*)

Use the pullup / -down functionality *pud* on the pin *pin*.

void **gpio_inp** (uint32_t *pin*)

Make pin *pin* an input.

void **gpio_out** (uint32_t *pin*)

Make pin *pin* an output.

5.1 Registers

struct **i2c_register_map**

This struct maps the registers of the BSC controller. The names of the struct members correspond to the registers from the [Datasheet](#):

```
struct i2c_register_map {  
    uint32_t C;  
    uint32_t S;  
    uint32_t DLEN;  
    uint32_t A;  
    uint32_t FIFO;  
    uint32_t DIV;  
    uint32_t DEL;  
    uint32_t CLKT;  
};
```

extern volatile struct *i2c_register_map* ***I2C**

```
I2C = (volatile struct i2c_register_map *)i2c_base_ptr;
```

By using this variable, the registers of the I2C can be accessed like this `I2C->FIFO`.

5.2 Functions

int **i2c_map**(void)

This function maps the I2C registers. It calls *peripheral_map()* with the values `I2C_OFFSET` and `I2C_SIZE`. `I2C_OFFSET` is defined in `i2c.c`. On error -1 is returned.

void **i2c_unmap**(void)

This function unmaps the I2C registers.

void **i2c_set_address** (uint8_t *addr*)

This function sets the address of the I2C device to communicate with. The address is a seven bit value.

void **i2c_set_clkdiv** (uint16_t *divisor*)

This function sets the clock divisor of the BSC controller.

Note: The clock source is the core clock with a frequency, according to the [Datasheet](#), of 150 MHz and according to [this file](#) and other sources of 250 MHz. When I tested the clock speed of I2C and SPI with a logic analyzer, it seems that 250 MHz **is correct** (at least for the Raspberry Pi Zero I use).

void **i2c_set_clkstr** (uint16_t *clkstr*)

This function sets the clock stretch timeout (or delay). This means that the master will wait *clkstr* cycles after the rising clock edge for the slave to respond. After this the timeout flag is set. This can often be left at reset value 0x40.

void **i2c_start** (void)

Starts the BSC controller and clears the flag register.

void **i2c_stop** (void)

Disables the BSC controller.

void **i2c_write_byte** (uint8_t *byte*)

Write a byte of data.

uint8_t **i2c_read_byte** (void)

This function receives a byte of data and returns it.

void **i2c_write_data** (const uint8_t **data*, uint16_t *length*)

This function writes *length* bytes of data pointed to by *data*.

void **i2c_read_data** (uint8_t **data*, uint16_t *length*)

This function receives *length* bytes of data and writes them to the array *data*.

void **i2c_write_register** (uint8_t *reg*, uint8_t *data*)

This function writes to bytes of data. First *reg* and then *data*.

Note: You *cannot* use two calls to *i2c_write_byte()* instead of this function because this is only *one* transmission, while two times *i2c_write_byte()* would be *two* different transmissions.

uint8_t **i2c_read_register** (uint8_t *reg*)

In contrast to *i2c_write_register()* you *can* use a call to *i2c_write_byte()* and to *i2c_read_byte()*. This is because I2C needs to make two transmissions anyway to change the read / write bit.

5.2.1 Useful Values

I2C_FIFO_SIZE	The size of the I2C FIFO
I2C_C_I2CEN	Enable I2C
I2C_C_ST	Start transfer
I2C_C_CLEAR	Clear the FIFO
I2C_C_READ	This transfer read from the slave
I2C_S_RXS	FIFO can be read
I2C_S_TXD	FIFO is full
I2C_S_DONE	Transfer done

Note: The [Datasheet](#) specifies PWM channels 0 and 1. The Raspberry Pi has pins for PWM channels 1 and 2, you just need to add one.

6.1 Macros

RNG_CHANNEL0

DAT_CHANNEL0

RNG_CHANNEL1

DAT_CHANNEL1

```
#define RNG_CHANNEL0    PWM->RNG1
#define DAT_CHANNEL0    PWM->DAT1
#define RNG_CHANNEL1    PWM->RNG2
#define DAT_CHANNEL1    PWM->DAT2
```

To prevent confusion (because the [Datasheet](#) calls the PWM channels 1 and 2 and the Raspberry Pi 0 and 1) the values of the registers which need to be used “on the fly” are :code;‘defined‘ from 2 to 1 and from 1 to 0.

6.2 Registers

struct **pwm_register_map**

This struct maps the registers of the PWM. The names of the struct members correspond to the registers from the [Datasheet](#):

```
struct pwm_register_map {
    uint32_t CTL;
    uint32_t STA;
    uint32_t DMAC;
    uint32_t: 32;
    uint32_t RNG1;
    uint32_t DAT1;
    uint32_t FIF1;
    uint32_t: 32;
    uint32_t RNG2;
    uint32_t DAT2;
};
```

extern volatile struct *pwm_register_map* ***PWM**

```
PWM = (volatile struct pwm_register_map *)pwm_base_ptr;
```

By using this variable, the registers of the PWM can be accessed like this `PWM->RNG1`.

6.3 Enums

6.3.1 PWM channel number

This enum holds the values distinguishing PWM channel 0 and 1:

```
enum {
    PWM_CHANNEL0, PWM_CHANNEL1
};
```

6.4 Structs

pwm_channel_config

This struct is used to configure a PWM channel:

```
typedef struct {
    union {
        struct {
            uint32_t: 1;
            uint32_t mode: 1;
            uint32_t rpt1: 1;
            uint32_t sbit: 1;
            uint32_t pola: 1;
            uint32_t usef: 1;
            uint32_t: 1;
            uint32_t msen: 1;
        };
        uint32_t ctl_register;
    };
    unsigned int divisor;
    uint32_t range;
} pwm_channel_config;
```

uint32_t **ctl_register**

This member can be directly edited by the anonymous struct inside this union. This register maps directly to the CTL register, with some offset for PWM 1. The settings of this register are described in the *Macros*.

unsigned int **divisor**

The divisor which is passed to the *Clock Manager*.

uint32_t **range**

The range to which the PWM counter counts before it starts over.

6.5 Functions

int **pwm_map**(void)

This function maps the PWM registers. It calls *peripheral_map()* with the values PWM_OFFSET and PWM_SIZE. On error -1 is returned.

void **pwm_unmap**(void)

This function unmaps the PWM registers.

void **pwm_configure**(int channel, *pwm_channel_config* *config)

This function configures channel with a *pwm_channel_config* pointed to by config.

void **pwm_enable**(int channel)

This function enables channel.

void **pwm_disable**(int channel)

This function disables channel.

6.5.1 Configuration Values

PWM_CTL_MODE_PWM	Use PWM mode
PWM_CTL_MODE_SERIALISER	Use serialiser mode
PWM_RPTL_STOP	If serialiser mode: Transmission stops when fifo empty
PWM_RPTL_REPEAT	If serialiser mode: Repeat last data when fifo empty
PWM_SBIT_LOW	Output low when no transmission active
PWM_SBIT_HIGH	Output high when no transmission active
PWM_POLA_DEFAULT	Polarity is default
PWM_POLA_INVERTED	Polarity is innverted
PWM_USEF_DATA	Data register is transmitted
PWM_USEF_FIFO	Data from fifo is transmitted
PWM_MSEN_PWMALGORITHM	Use PWM algorithm
PWM_MSEN_MS_RATIO	Use MS ratio

7.1 Registers

struct **spi_register_map**

This struct maps the registers of the SPI. The names of the struct members correspond to the registers from the [Datasheet](#):

```
struct spi_register_map {
    uint32_t CS;
    uint32_t FIFO;
    uint32_t CLK;
    uint32_t DLEN;
    uint32_t LTOH;
    uint32_t DC;
};
```

extern volatile struct *spi_register_map* ***SPI**

```
SPI = (volatile struct spi_register_map *)spi_base_ptr;
```

By using this variable, the registers of the SPI can be accessed like this `SPI->CS`.

7.2 Structs

spi_channel_config

This struct is used to configure SPI:

```
typedef struct {
    union {
        struct {
```

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```

        uint32_t: 2;
        uint32_t cpha: 1;
        uint32_t cpol: 1;
        uint32_t: 2;
        uint32_t cspol: 1;
        uint32_t: 14;
        uint32_t cspol0: 1;
        uint32_t cspol1: 1;
        uint32_t cspol2: 1;
    };
    uint32_t cs_register;
};

    uint16_t divisor;
} spi_channel_config;

```

uint32_t cs_register

This member can be directly edited by the anonymous struct inside this union. This register maps directly to the CS register. The settings of this register are described in the ‘**Macros**’_.

uint16_t divisor

The master clock divisor.

Note: The clock source is the core clock with a frequency, according to the [Datasheet](#), of 150 MHz and according to [this file](#) and other sources of 250 MHz. When I tested the clock speed of I2C and SPI with a logic analyzer, it seems that 250 MHz **is correct** (at least for the Raspberry Pi Zero I use).

7.3 Functions

int spi_map (void)

This function maps the SPI registers. It calls *peripheral_map()* with the values SPI_OFFSET and SPI_SIZE. On error -1 is returned.

void spi_unmap (void)

This function unmaps the SPI registers.

void spi_configure (spi_channel_config *config)

This function configures SPI with a *spi_channel_config* pointed to by config.

void spi_set_ce (uint8_t ce)

This function sets which chip enable line the SPI controller should use. This can be a 3 bit value.

void spi_transfer_start (void)

This function starts a SPI transfer.

void spi_transfer_stop (void)

This function stops the current SPI transfer.

uint8_t spi_transfer_byte (uint8_t data)

While there is a SPI transfer active you can call this function as often as needed by the slave, to send and receive. This function needs to be called between *spi_transfer_start()* and *spi_transfer_stop()*, it sends data over SPI and asynchronously receives data and *returns* it.

uint8_t **spi_send2_recv1** (uint8_t *data0*, uint8_t *data1*)

This function writes to bytes of data and than keeps the clock running to receive and return the third byte.
spi_transfer_start() and *spi_transfer_stop()* *may not* be called when using this function.

7.3.1 CS Register Bit Values

SPI_CS_CE0	Use chip enable 0
SPI_CS_CE1	Use chip enable 1
SPI_CS_CE2	Use chip enable 2
SPI_CPHA_CLK_BEGINNING	Data on clock leading edge
SPI_CPHA_CLK_MIDDLE	Data on clock trailing edge
SPI_CPOL_RESET_LOW	Clock polarity: active low
SPI_CPOL_RESET_HIGH	Clock polarity: active high
SPI_CSPOL_ACTIVE_LOW	Chip enable: active low
SPI_CSPOL_ACTIVE_HIGH	Chip enable: active high

8.1 Registers

struct **timer_register_map**

This struct maps the registers of the timer. The names of the struct members correspond to the registers from the [Datasheet](#):

```
struct i2c_register_map {
    uint32_t CS;
    uint32_t CLO;
    uint32_t CHI;
    uint32_t C0;
    uint32_t C1;
    uint32_t C2;
    uint32_t C3;
};
```

extern volatile struct *timer_register_map* ***TMR**

```
TMR = (volatile struct timer_register_map *)timer_base_ptr;
```

By using this variable, the registers of the timer can be accessed like this `TMR->CLO`.

8.2 Functions

int **timer_map** (void)

This function maps the timer registers. It calls *peripheral_map()* with the values `TIMER_OFFSET` and `TIMER_SIZE`. On error -1 is returned.

void **timer_unmap** (void)

This function unmaps the timer registers.

```
void timer_read(uint64_t *counter);
```

This function reads the value of the timer into the 64-bit variable pointed to by `counter`.

The `mipea.c / h` files are just a wrapper for all the other parts of the library. If you are lazy (or need all peripherals mapped) than this wrapper is usefull.

9.1 Functions

int **mipea_map** (void)

This function maps all the peripherals and returns `-1` on error.

void **mipea_unmap** (void)

This function unmaps all the peripherals.

CHAPTER 10

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CHAPTER 11

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CHAPTER 12

Indices and tables

- `genindex`
- `modindex`
- `search`

C

Clock Manager, 4
 clock_configure (*C function*), 6
 clock_disable (*C function*), 6
 clock_enable (*C function*), 6
 clock_manager_register_map (*C type*), 5
 clock_map (*C function*), 6
 clock_unmap (*C function*), 6
 CM (*C variable*), 5

D

DAT_CHANNEL0 (*C macro*), 13
 DAT_CHANNEL1 (*C macro*), 13

G

GP (*C variable*), 8
 gpio_clr (*C function*), 9
 gpio_func (*C function*), 9
 gpio_inp (*C function*), 9
 gpio_map (*C function*), 8
 gpio_out (*C function*), 9
 gpio_pud (*C function*), 9
 gpio_register_map (*C type*), 7
 gpio_set (*C function*), 9
 gpio_tst (*C function*), 9
 gpio_unmap (*C function*), 8
 GPIOs, 6

I

I2C, 9
 I2C (*C variable*), 11
 i2c_map (*C function*), 11
 i2c_read_byte (*C function*), 12
 i2c_read_data (*C function*), 12
 i2c_read_register (*C function*), 12
 i2c_register_map (*C type*), 11
 i2c_set_address (*C function*), 12
 i2c_set_clkdiv (*C function*), 12
 i2c_set_clkstr (*C function*), 12

i2c_start (*C function*), 12
 i2c_stop (*C function*), 12
 i2c_unmap (*C function*), 11
 i2c_write_byte (*C function*), 12
 i2c_write_data (*C function*), 12
 i2c_write_register (*C function*), 12
 Installation, 1

M

Mipea Wrapper, 22
 mipea_map (*C function*), 23
 mipea_unmap (*C function*), 23

P

PERIPHERAL_BASE_BCM2835 (*C macro*), 3
 PERIPHERAL_BASE_BCM2836_7 (*C macro*), 3
 peripheral_ismapped (*C function*), 4
 peripheral_map (*C function*), 3
 peripheral_unmap (*C function*), 3
 Peripherals, 2
 PWM, 13
 PWM (*C variable*), 14
 pwm_channel_config (*C type*), 14
 pwm_channel_configctl_register (*C member*), 14
 pwm_channel_config.divisor (*C member*), 15
 pwm_channel_config.range (*C member*), 15
 pwm_configure (*C function*), 15
 pwm_disable (*C function*), 15
 pwm_enable (*C function*), 15
 pwm_map (*C function*), 15
 pwm_register_map (*C type*), 13
 pwm_unmap (*C function*), 15

R

RNG_CHANNEL0 (*C macro*), 13
 RNG_CHANNEL1 (*C macro*), 13

S

SPI, 15

SPI (*C variable*), [17](#)
spi_channel_config (*C type*), [17](#)
spi_channel_config.cs_register (*C member*), [18](#)
spi_channel_config.divisor (*C member*), [18](#)
spi_configure (*C function*), [18](#)
spi_map (*C function*), [18](#)
spi_register_map (*C type*), [17](#)
spi_send2_recv1 (*C function*), [18](#)
spi_set_ce (*C function*), [18](#)
spi_transfer_byte (*C function*), [18](#)
spi_transfer_start (*C function*), [18](#)
spi_transfer_stop (*C function*), [18](#)
spi_unmap (*C function*), [18](#)

T

Timer, [19](#)
timer_map (*C function*), [21](#)
timer_register_map (*C type*), [21](#)
timer_unmap (*C function*), [21](#)
TMR (*C variable*), [21](#)
Troubleshooting, [1](#)